

## CLAIMS

1. A navigation apparatus comprising:

a deviation judging unit that judges whether a moving object has deviated from a guided route to a destination;

5 a distance calculating unit that calculates the distance from a deviated point to a planned route point when the moving object has been judged by the deviation judging unit to have deviated from the guided route before the moving object transits the planned route point present  
10 on the guided route;

a route judging unit that judge whether the planned route point is transited based on a distance history calculated by the distance calculating unit; and

a re-searching unit that re-searches a guided route  
15 based on the result of the judgment by the transit judging unit.

2. The navigation apparatus according to claim 1, wherein, when the distance tends to increase, the transit judging  
20 unit judge that the planned route point is not transited.

3. The navigation apparatus according to claim 1, wherein a first planned route point to be guided first and a second planned route point to be guided next to the first  
25 planned route point are present on the guided route,  
the distance calculating unit calculates a first

distance that is a distance from the deviated point to the first planned route point and a second distance that is a linear distance from the deviated point to the second planned route point, when the moving object has been judged  
5 by the deviation judging unit 101 to have deviated from the guided route before the moving object transits the first planned route point, and

the transit judging unit judges whether the first planned route point is transited, based on the first  
10 distance history and the second distance history calculated by the distance calculating unit.

4. The navigation apparatus according to claim 3, wherein  
when the first distance tends to increase and the  
15 second distance tends to decrease, the transit judging unit judges the first planned route point to be not transited, and

the re-searching unit re-searches a guided route that does not transit the first planned route point and transits  
20 the second planned route point.

5. The navigation apparatus according to any one of claims 1 to 4, further comprising a presenting unit that, when the planned route point has been judged by the transit  
25 judging unit not to be transited, presents the result of this judgment.

6. The navigation apparatus according to any one of claims 1 to 4, further comprising:

5 a presenting unit that presents confirmation of whether the planned route point is transited when the planned route point has been judged by the transit judging unit not to be transited; and

an acquiring unit that acquires instruction information in response to the confirmation presentation by  
10 the presenting unit, and wherein

the re-searching unit re-searches a guided route based on the instruction information.

7. The navigation apparatus according to any one of  
15 claims 1 to 4, wherein the transit judging unit judge the planned route point to be transited when the distance from the deviated point to the planned route point is larger than a predetermined value.

20 8. A route searching method comprising:

a deviation judging step of judging whether a moving object has deviated from a guided route to a destination;

a distance calculating step of calculating the distance from a deviated point to a planned route point  
25 when the moving object has been judged at the deviation judging step to have deviated from the guided route before

the moving object transits the planned route point present on the guided route;

a transit judging step of judging whether the planned route point is transited based on a distance history

5 calculated at the distance calculating step; and

a re-searching step of re-searching a guided route based on the result of the judgment at the transit judging step.

10 9. A route searching program that causes a computer to execute the route searching method according to claim 8.

10. A computer-readable recording medium that records the route searching program according to claim 9.